

## Koala BEAR Muscle Build (KBMB01) Proprioceptive Actuator

Properties & Specifications

Rev A 08/23/2023

## 1 Working Environment

Temperature of working environment:<45  $^{\circ}$ C  $_{\circ}$ 

## 2 Technical Specs

Input Voltage	9~48V*
Max Phase Current	30A
Max Input Current	<15A
Continuous Torque**	6N.m
Peak Torque	≥ 18N.m
No-load Max Speed	7 RPM/V
Avrg. Backdrive Torque	≤ 1.2Nm
Weight	~285g
Pole Pair	20
Gear Ratio	20
Power Port	XT30 Male
Power Input	DC Power
Signal Port	Molex PicoBlade 53047 6Pin or similar(P=1.25mm)
Signal Protocol	RS485,最高 8Mb/S
Winding Temperature Rating	180℃
Dimension	Hexagon Diameter of Inscribed Circle: 75mm Distance Between Sides: 67mm Height: 37.5mm
Absolute Position	Yes
Material	7075-T6
Protection	<ul> <li>Configurable torque timit</li> <li>Configurable speed limit</li> <li>Configurable acceleration limit</li> <li>Configurable position limit</li> <li>Two-stage over-temperature protection</li> <li>Communication watchdog in Torque Mode</li> </ul>
Standard iq/id PID	P=0.3~0.4 (0.358) I=0.03~0.077 (0.045) D=0
Service Life ***	≥ 5000h

<sup>\*</sup> When the input voltage exceeds 24V, the heat dissipation requirements may be more stringent.

<sup>\*\*</sup> Under continuous torque output conditions, intermittent air cooling is necessary to maintain a certain air convection and heat dissipation efficiency.

<sup>\*\*\*</sup> Overloading and overheating can reduce service life.